

# Mean Field Game Master Equations with Monotonicity and Anti-monotonicity Conditions in Displacement Sense

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# Outline

- 1 Introduction
- 2 Stochastic calculus on Wasserstein space
- 3 Derivation of our (anti-)monotonicity condition
- 4 The global wellposedness

# $N$ -player games

- A large system :  $i = 1, \dots, N$ ,

$$X_t^{i, \alpha^i} = x_i + \int_0^t \alpha_s^i(X_s^{i, \alpha^i}) ds + B_s^i; \quad \mu_s^{N, \vec{\alpha}} := \frac{1}{N} \sum_{i=1}^N \delta_{X_s^{i, \alpha^i}}.$$

- $J_i(0, \vec{x}, \vec{\alpha}) := \mathbf{E} \left[ G(X_T^{i, \alpha^i}, \mu_T^{N, \vec{\alpha}}) + \int_0^T F(X_s^{i, \vec{\alpha}}, \mu_s^{N, \vec{\alpha}}, \alpha_s^i) ds \right]$

- Nash equilibrium  $\vec{\alpha}^*$  :

$$J_i(0, \vec{x}, \vec{\alpha}^*) \leq J_i(0, \vec{x}, \vec{\alpha}^{*, -i}, \alpha^i), \quad \forall \alpha^i, \forall i.$$

- The goal :  $N \rightarrow \infty$  ?

# Mean field games

- The "others" : everybody using the **same**  $\alpha$ ,

$$X_t^{\xi, \alpha} = \xi + \int_0^t \alpha_s(X_s^{\xi, \alpha}) ds + B_s; \quad \mu_s^\alpha := \mathcal{L}_{X_s^{\xi, \alpha}}.$$

- The individual player : using  $\alpha'$ ,

$$X_t^{x, \alpha'} = x + \int_0^t \alpha'_s(X_s^{x, \alpha'}) ds + B_s;$$

$$J(0, \xi, \alpha; x, \alpha') := \mathbf{E} \left[ G(X_T^{x, \alpha'}, \mu_T^\alpha) + \int_0^T F(X_s^{x, \alpha'}, \mu_s^\alpha, \alpha'_s) ds \right].$$

# Mean field equilibrium

- Mean field equilibrium  $\alpha^*$  :

$$J(0, \xi, \alpha^*; x, \alpha^*) \leq J(0, \xi, \alpha^*; x, \alpha'), \quad \forall \alpha', \forall x.$$

- When MFE  $\alpha^*$  is unique, introduce the value function

$$V(t, x, \mu) := J(t, \xi, \alpha^*; x, \alpha^*).$$

Our goal is to study the **master equation** for  $V$ .

- Caines-Huang-Malhame (2006), Lasry-Lions (2007);  
Cardaliaguet (2010), Carmona-Delarue (2018)

# The master equation

The **global** wellposedness of the master equation required :

- Sufficiently **smooth** data  $F, G$
- $F$  **separable** :  $F(x, \mu, \alpha) = F_0(x, \mu) + F_1(x, \alpha)$ .
- $G, F_0$  **monotone** (in Lasry-Lions sense or in displacement sense)
- The literature for global solution :
  - ◇ Buckdahn-Li-Peng-Rainer (2017) ;
  - ◇ Chassagneux-Crisan-Delarue (2014), Carmona-Delarue (2018), Cardaliaguet-Delarue-Lasry-Lions (2019), Mou-Z. (2019)
  - ◇ Gangbo-Mezzaros (2020), Bensoussan-Graber-Yam (2020)
  - ◇ Bayraktar-Cohen (2018), Bertucci-Lasry-Lions (2019), Bayraktar-Cecchin-Cohen-Delarue (2019)

# Our main contributions

- Non-separable  $F$
- New types of monotonicity and anti-monotonicity conditions
- A new approach to find the appropriate conditions
  
- Gangbo-Meszaros-Mou-Z. (2021), Mou-Z. (2021 ?)

# Our strategy

Monotonicity of data

Monotonicity of  $V$

Global wellposedness of master equation



# Our strategy (cont.)

Anti-Monotonicity of data

Anti-Monotonicity of  $V$

Global wellposedness of master equation

# Outline of the talk

- Stochastic calculus on Wasserstein space
- Derivation of our (anti-)monotonicity condition
- The global wellposedness
- For simplicity
  - ◇  $d = 1$
  - ◇ No common noise

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# Wasserstein derivatives

- $\mathcal{P}_2 = \mathcal{P}_2(\mathbb{R})$ , Wasserstein distance  $W_2$
- For  $U : \mathcal{P}_2 \rightarrow \mathbb{R}$ , linear derivative  $\delta_\mu U : \mathcal{P}_2 \times \mathbb{R} \rightarrow \mathbb{R}$ 
  - ◇  $\lim_{\varepsilon \rightarrow 0} \frac{U(\mu + \varepsilon(\nu - \mu)) - U(\mu)}{\varepsilon} = \int_{\mathbb{R}} \delta_\mu U(\mu, x) [\nu(dx) - \mu(dx)]$
  - ◇ Wasserstein derivative  $\partial_\mu U(\mu, x) = \partial_x \delta_\mu U(\mu, x)$
- For  $U : (t, x, \mu) \in [0, T] \times \mathbb{R} \times \mathcal{P}_2 \rightarrow \mathbb{R}$ ,
  - ◇  $\partial_t U, \partial_x U, \partial_{xx} U$  are standard
  - ◇  $\delta_\mu U(t, x, \mu, \tilde{x})$  and higher order derivatives in obvious sense

## Ito formula

- Let  $U(t, x, \mu)$  be smooth, and  $dX_t = b_t dt + \sigma_t dB_t$

$$dU(t, X_t, \mathcal{L}_{X_t}) = \partial_t U dt + \partial_x U dX_t + \frac{1}{2} \partial_{xx} U \sigma_t^2 dt \\ + \tilde{E} \left[ \frac{1}{2} \partial_{\tilde{x}\mu} U(t, X_t, \mathcal{L}_{X_t}, \tilde{X}_t) \tilde{\sigma}_t^2 + \partial_\mu U(t, X_t, \mathcal{L}_{X_t}, \tilde{X}_t) \tilde{b}_t \middle| \mathcal{F}_t^X \right] dt$$

- ◇  $(\tilde{X}, \tilde{b}, \tilde{\sigma})$  is an independent copy of  $(X, b, \sigma)$
- ◇ Buckdahn-Li-Peng-Rainer (2017), Chassagneux-Crisan-Delarue (2014)

# Hamiltonian

- MFG :

$$dX_t = \alpha_t^* dt + dB_t;$$

$$V_0 = E \left[ G(X_T, \mathcal{L}_{X_T}) + \int_0^T F(X_t, \mathcal{L}_{X_t}, \alpha_t^*) dt \right]$$

- Hamiltonian  $H(x, \mu, p) := \inf_a [ap + F(x, \mu, a)]$

$$\diamond \partial_{pp} H < 0$$

$$\diamond a^* = \partial_p H(t, x, \mu, p)$$

- Separability :

$$F = F_0(x, \mu) + F_1(x, a) \implies H = F_0(x, \mu) + H_1(x, p)$$

# Master equation

- DPP + Ito formula  $\implies$  PDE
- Master equation for  $V(t, x, \mu)$

$$\begin{aligned}
 0 &= \partial_t V + \frac{1}{2} \partial_{xx} V + \partial_x V \partial_p H(x, \mu, \partial_x V(t, x, \mu)) \\
 &+ \tilde{E} \left[ \frac{1}{2} \partial_{\tilde{x}\mu} V(t, x, \mu, \tilde{\xi}) + \partial_\mu V(t, x, \mu, \tilde{\xi}) \partial_p H(\tilde{\xi}, \mu, \partial_x V(t, \tilde{\xi}, \mu)) \right]; \\
 V(T, x, \mu) &= G(x, \mu).
 \end{aligned}$$

- ◇ Optimal control :  $\alpha_t^* = \partial_p H(X_t, \mathcal{L}_{X_t}, \partial_x V(t, X_t, \mathcal{L}_{X_t}))$
- ◇ Non-local equation, comparison principle fails

# Monotonicity conditions

- Lasry-Lions monotonicity condition

$$E \left[ G(\xi_1, \mathcal{L}_{\xi_1}) + G(\xi_2, \mathcal{L}_{\xi_2}) - G(\xi_1, \mathcal{L}_{\xi_2}) - G(\xi_2, \mathcal{L}_{\xi_1}) \right] \geq 0;$$

or equivalently  $\tilde{E} \left[ \partial_{x\tilde{x}} \delta_\mu G(\xi, \mathcal{L}_\xi, \tilde{\xi}) \eta \tilde{\eta} \right] \geq 0, \quad \forall \xi, \eta$

- Displacement monotonicity condition

$$\tilde{E} \left[ \partial_{x\tilde{x}} \delta_\mu G(\xi, \mathcal{L}_\xi, \tilde{\xi}) \eta \tilde{\eta} + \partial_{xx} G(\xi, \mathcal{L}_\xi) \eta^2 \right] \geq 0, \quad \forall \xi, \eta \quad (1)$$

- For potential games :  $G(x, \mu) = \delta_\mu \mathcal{G}(\mu, x)$  for some  $\mathcal{G} : \mathcal{P}_2 \rightarrow \mathbb{R}$ 
  - Lasry-Lions monotonicity means :  $\mu \in \mathcal{P}_2 \rightarrow \mathcal{G}(\mu)$  is convex
  - Displacement monotonicity means :  $\xi \in \mathbb{L}^2 \rightarrow \mathcal{G}(\mathcal{L}_\xi)$  is convex



## A motivating example

- Lasry-Lions :  $G(x, \mu) = (x - m_\mu)^2$ , where  $m_\mu := \int x \mu(dx)$

$$\partial_{x\tilde{x}} \delta_\mu G(x, \mu, \tilde{x}) = -2,$$

$$\tilde{E} \left[ \partial_{x\tilde{x}} \delta_\mu G(\xi, \mathcal{L}_\xi, \tilde{\xi}) \eta \tilde{\eta} \right] = -2 |\mathbf{E}[\eta]|^2 \leq 0.$$

- Carmona-Cooney-Graves-Lauriere :

$$G(x, \mu) = (x - m_\mu)^2 + (x - x_0)^2$$

- Displacement anti-monotonicity :

$$G(x, \mu) = (x - m_\mu)^2 - (x - x_0)^2$$

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# Characteristics

- Given  $\xi, \eta$ ,

$$X_t = \xi + \int_0^t \partial_p H(X_s, \mu_s, \partial_x V(s, X_s, \mu_s)) ds + B_t, \quad \mu_t := \mathcal{L}_{X_t};$$

$$\delta X_t = \eta + \int_0^t \left[ H_{px}(X_s) \delta X_s + \frac{1}{2} \tilde{E}_{\mathcal{F}_t} [H_{p\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t] + H_{pp}(X_s) N_s \right] ds,$$

$$N_t := \tilde{E}_{\mathcal{F}_t} [\partial_{x\mu} V(X_t, \tilde{X}_t) \delta \tilde{X}_t] + \partial_{xx} V(X_t) \delta X_t + \frac{\tilde{E}_{\mathcal{F}_t} [H_{p\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t]}{2H_{pp}(X_t)}$$

$$\diamond \delta X_t = \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} [X_t^{\xi + \varepsilon \eta} - X_t^\xi]$$

# The main idea

- For Lasry-Lions monotonicity, want

$$I'_{LL}(t) \leq 0, \quad I_{LL}(t) := \tilde{\mathbb{E}} \left[ \partial_{x\mu} V(t, X_t, \mu_t, \tilde{X}_t) \delta X_t \delta \tilde{X}_t \right].$$

- Notice that  $V(T, \cdot) = G$ ,

$G$  L-L mon  $\Leftrightarrow I_{LL}(T) \geq 0 \Rightarrow I_{LL}(0) \geq 0 \Leftrightarrow V(0, \cdot, \cdot)$  L-L mon

- Ito formula + master equation to analyze  $I'_{LL}(t)$

## The key calculation

- The non-separable case

$$\begin{aligned}
 I'_{LL}(t) = & \tilde{\mathbb{E}} \left[ H_{pp}(X_t) \left| \tilde{\mathbb{E}}_{\mathcal{F}_t} \left[ \partial_{x\mu} V(X_t, \tilde{X}_t) \delta \tilde{X}_t + \frac{H_{p\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t}{2H_{pp}(X_t)} \right] \right|^2 \right. \\
 & - \partial_{xx} V(X_t) H_{p\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t \delta X_t \\
 & \left. - H_{x\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t \delta X_t - \frac{\left| \tilde{\mathbb{E}}_{\mathcal{F}_t} [H_{p\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t] \right|^2}{4H_{pp}(X_t)} \right].
 \end{aligned}$$

- The separable case :  $H = H_0(x, \mu) + H_1(x, p)$ , and  $H_{pu} = 0$ ,

$$I'_{LL}(t) = \tilde{\mathbb{E}} \left[ H_{pp}(X_t) \left| \tilde{\mathbb{E}}_{\mathcal{F}_t} \left[ \partial_{x\mu} V(X_t, \tilde{X}_t) \delta \tilde{X}_t \right] \right|^2 - H_{x\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t \delta X_t \right]$$

- Need :  $H_0$  is Lasry-Lions monotone

## Displacement monotonicity

$$\begin{aligned}
I'_D(t) &:= \frac{d}{dt} \tilde{\mathbf{E}} \left[ \partial_{x\mu} V(X_t, \tilde{X}_t) \delta X_t \delta \tilde{X}_t + \partial_{xx} V(X_t) |\delta X_t|^2 \right] \\
&= \tilde{\mathbf{E}} \left[ H_{pp}(X_t) \left| \tilde{\mathbf{E}}_{\mathcal{F}_t} \left[ V_{x\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t + V_{xx}(X_t) \delta X_t + \frac{H_{p\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t}{2H_{pp}(X_t)} \right] \right|^2 \right. \\
&\quad \left. - H_{x\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t \delta X_t - H_{xx}(X_t) |\delta X_t|^2 - \frac{|\tilde{\mathbf{E}}_{\mathcal{F}_t} [H_{p\mu}(X_t, \tilde{X}_t) \delta \tilde{X}_t]|^2}{4H_{pp}(X_t)} \right].
\end{aligned}$$

- Our monotonicity condition

$$\tilde{\mathbf{E}} \left[ H_{x\mu}(\xi, \tilde{\xi}) \eta \tilde{\eta} + H_{xx}(\xi) \eta^2 + \frac{|\tilde{\mathbf{E}}_{\mathcal{F}_t} [H_{p\mu}(\xi, \tilde{\xi}) \tilde{\eta}]|^2}{4H_{pp}(\xi)} \right] \geq 0 \quad (2)$$

- The separable case :  $H = H_0(x, \mu) + H_1(x, p)$ , and  $H_{pu} = 0$ ,  
  - ◊ Need :  $H_0$  is displacement monotone

# Displacement anti-monotonicity

- Recall

$$I_D(t) := \tilde{\mathbf{E}} \left[ \partial_{x\mu} V(X_t, \tilde{X}_t) \delta X_t \delta \tilde{X}_t + \partial_{xx} V(X_t) |\delta X_t|^2 \right]$$

- Denote

$$J_D(t) := \mathbf{E} \left[ \left| \tilde{\mathbf{E}}_{\mathcal{F}_T} \left[ \partial_{x\mu} V(X_t, \tilde{X}_t) \delta \tilde{X}_t \right] \right|^2 + \left| \partial_{xx} V(X_t) \delta X_t \right|^2 \right] \geq 0.$$

- Anti-monotonicity : for some appropriate constant  $c > 0$ ,

$$I_D(t) + cJ_D(t) \leq 0 \quad \text{or equivalently} \quad I_D(t) \leq -cJ_D(t) \leq 0.$$

- $I_D(t)$  and  $J_D(t)$  involve different orders of  $\partial_{xx} V$  and  $\partial_{x\mu} V$ , so we need precise estimates on their bounds, in particular,  $\partial_{xx} V < 0$ .

# Propagation of anti-monotonicity

- Assume  $G$  satisfies :  $I_D(T) + cJ_D(T) \leq 0$
- Assume  $H$  satisfies certain condition which gives us appropriate estimates on  $\partial_{xx} V$  (and  $\partial_{x\mu} V$ )

- The crucial estimation :

$$I'_D(t) + cJ'_D(t) \geq 0 \implies I_D(t) + cJ_D(t) \leq 0, \forall t.$$

- In the [separable](#) case, we may consider Lasry-Lions anti-monotonicity in the same manner :

$$\tilde{\mathbb{E}} \left[ \partial_{x\mu} V(X_t, \tilde{X}_t) \delta X_t \delta \tilde{X}_t + \left| \tilde{\mathbb{E}}_{\mathcal{F}_T} [\partial_{x\mu} V(X_t, \tilde{X}_t) \delta \tilde{X}_t] \right|^2 \right] \leq 0.$$



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# Assumptions

- (Areg) :  $H, G$  are sufficiently smooth and  $H_{pp} \leq -c_0 < 0$
  - (AG) :  $G$  satisfies displacement monotonicity condition (1)
  - (AH) :  $H$  satisfies our monotonicity condition (2)
  - (AV) :  $V$  is a sufficiently smooth solution of the master equation
- The conditions in the anti-monotonicity case are more involved. We skip them here. Once we obtain the propagation of the anti-monotonicity, the remaining proof of the global wellposedness is the same as the monotone case presented at below.

# Propagation of displacement monotonicity

## Theorem 1

Under (Areg), (AG), (AH), and (AV), then  $V$  satisfies the displacement monotonicity condition (1).

# Uniform Lipschitz continuity of $V$

## Theorem 2

Under (Areg) and (AV), if  $V$  satisfies the Lasry-Lions monotonicity condition or the displacement monotonicity condition, then  $V$  is **uniformly Lipschitz continuous** in  $x$  and  $\mu$

- In Theorem 2, we do not assume monotonicity condition directly on  $H$ .

# Global wellposedness

## Theorem 3

Under (Areg), (AG), and (AH), then the master equation has a unique classical solution  $V$

- Local classical solution + Uniform Lipschitz continuity  
 $\implies$  Global classical solution

# A final remark

The **monotonicity condition** is for the

- uniqueness of mean field equilibrium
- existence of global solution
- **not for the uniqueness of global solution**

Thank you very much for your attention !